

A High-Order Local Discontinuous Galerkin Method for the p -Laplace Equation

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Highlights

- Efficient preconditioner with hk -independent performance.
- High-order error estimates assuming high regularity.
- Estimates under a non-equivalent distance from existing ones.

Notations

- \mathcal{T}_h : a quasi-uniform simplicial mesh discretization of Ω .
- $\Gamma^o, \Gamma^D, \Gamma^N$: the unions of interior, Dirichlet and Neumann faces.
- $[\cdot], \{\{\cdot\}\}$: the DG jump and average operators on faces.
- Π_V : the L^2 projection onto a linear space V .
- Q_h, Σ_h, V_h : DG spaces for q, σ and u (k -th order piecewise polynomial).
- $(\cdot; \cdot), \langle \cdot; \cdot \rangle$: weighted L^2 inner product on d - and $d-1$ -dimensional manifolds.

The p -Laplace equation

Let $\Omega \subset \mathbb{R}^d$ be a bounded Lipschitz domain, $p \in (1, +\infty)$, and define $\mathcal{A}(\tau) := |\tau|^{p-2} \tau$. The mixed and minimization forms of the p -Laplace equations are (1) and (2) respectively.

$$\begin{cases} \mathbf{q} - \nabla u = \mathbf{0} & \text{in } \Omega, \\ \sigma - \mathcal{A}(\mathbf{q}) = \mathbf{0} & \text{in } \Omega, \\ -\nabla \cdot \sigma = f & \text{in } \Omega, \\ u = g_D & \text{on } \Gamma^D, \\ \sigma \cdot \mathbf{n} = \mathbf{g}_N \cdot \mathbf{n} & \text{on } \Gamma^N. \end{cases} \quad (1) \quad \text{where } J(u) := \frac{1}{p} \|\nabla u\|_{L^p(\Omega)}^p - (f, u)_\Omega - \langle \mathbf{g}_N \cdot \mathbf{n}, u \rangle_{\Gamma^N}$$

$$\text{and } V = \left\{ v \in W^{1,p}(\Omega) : v|_{\Gamma^D} = g_D \right\} \quad (2)$$

Spatial discretization: the LDG method

Define the LDG weak gradient operator $D_{DG} : W^{1,1}(\mathcal{T}_h) \times L^1(\Gamma^D) \mapsto Q_h$ to be: $\forall \zeta_h \in \Sigma_h$,

$$(D_{DG}(v; g), \zeta_h)_\Omega = (\nabla_h v, \zeta_h)_\Omega - \langle [v], \{\{\zeta_h\}\} \rangle - C_{12} \langle \zeta_h \rangle_{\Gamma^o} - (v - g, \zeta_h \cdot \mathbf{n})_{\Gamma^D}.$$

The LDG discretization of (1) for $(\mathbf{q}_h, \sigma_h, u_h)$ is

$$\begin{aligned} \text{find } u_h \in V_h \text{ s.t. } & \forall v_h \in V_h, J'_h(u_h)(v_h) = 0, \\ & \mathbf{q}_h = D_{DG}(u_h; g_D), \\ & \sigma_h = \Pi_{\Sigma_h} \mathcal{A}(\mathbf{q}_h). \end{aligned}$$

The **equivalent** and **unsolvent** minimization form for u_h (also a LDG discretization of (2)) is

$$u_h \in \arg \min_{v_h \in V_h} J_h(v_h). \quad (3)$$

Here, $J'_h(u_h)(v_h)$ is the Gâteaux derivative of $J_h(u_h)$ on v_h direction.

$$\begin{aligned} J_h(v_h) &= \frac{1}{p} \|D_{DG}(v_h; g_D)\|_{L^p(\Omega)}^p + \frac{1}{p} \|[v_h]\|_{L^p(\Gamma^o, \eta h_e^{1-p})}^p \\ &\quad + \frac{1}{p} \|v_h - g_D\|_{L^p(\Gamma^D, \eta h_e^{1-p})}^p - (f, v_h)_\Omega - \langle \mathbf{g}_N \cdot \mathbf{n}, v_h \rangle_{\Gamma^N}. \\ J'_h(u_h)(v_h) &= (\mathcal{A}(D_{DG}(u_h; g_D)), D_{DG}(v_h; 0))_\Omega + \langle \eta \mathcal{A}(h_e^{-1}[u_h]), [v_h] \rangle_{\Gamma^o} \\ &\quad + \langle \eta \mathcal{A}(h_e^{-1}(u_h - g_D) \mathbf{n}), v_h \mathbf{n} \rangle_{\Gamma^D} - (f, v_h)_\Omega - \langle \mathbf{g}_N \cdot \mathbf{n}, v_h \rangle_{\Gamma^N}. \end{aligned}$$

Nonlinear solver: hk -independent preconditioned gradient descent

For J_h , the (unnormalized) steepest descent direction w_h at u_h under $\|\cdot\|$ (to be determined) is characterized by

$$J'_h(u_h)(w_h) = - \sup_{v_h \in V_h} \frac{J'_h(u_h)(v_h)}{\|v_h\|} \|w_h\|.$$

We choose the following linearized norm that is generalized from [Huang et al. 2007].

$$\|w_h\|^2 := \|D_{DG}(w_h; 0)\|_{L^2(\Omega, |D_{DG}(u_h; g_D)|^{p-2})}^2 + \|[w_h]\|_{L^2(\Gamma^o, \eta h_e^{1-p} |h_e^{-1} u_h|^{p-2})}^2 + \|w_h\|_{L^2(\Gamma^D, \eta h_e^{-1} |h_e^{-1}(u_h - g_D)|^{p-2})}^2.$$

Then the scheme for w_h (regularization terms in weights ignored) is an elliptic LDG scheme:

$$\begin{aligned} \text{find } w_h \in V_h \text{ such that } & \forall v_h \in V_h: \\ & (D_{DG}(w_h; 0); |D_{DG}(u_h; g_D)|^{p-2}; D_{DG}(v_h; 0))_\Omega + \langle \eta h_e^{-1} [w_h]; |h_e^{-1} [u_h]|^{p-2}; [v_h] \rangle_{\Gamma^o} \\ & + \langle \eta h_e^{-1} w_h; |h_e^{-1}(u_h - g_D)|^{p-2}; v_h \rangle_{\Gamma^D} = -J'_h(u_h)(v_h). \end{aligned}$$

Theorem 1: Error estimates for the primal variable [Wu and Xu 2023]

Define $\|v\|_{J,p} := \left(\|D_{DG}(v; 0)\|_{L^p(\Omega)}^p + \|[v]\|_{L^p(\Gamma^o, \eta h_e^{1-p})}^p \right)^{\frac{1}{p}}$. Assume $\eta = \Theta(1)$ and $C_{12} = \mathcal{O}(1)$. Let $(\mathbf{q}, \sigma, u) \in W^{s,p}(\Omega) \times (W^{r,p}(\Omega) \cap L^p(\text{div}, \Omega)) \times W^{s+1,p}(\Omega)$ be the exact solution. Assume WLOG that $s, r \in \mathbb{N}$ satisfy $s \leq k$ and $r \leq k+1$. Let $u_h^* := \Pi_{V_h} u$, then

$$\text{For } p \in (1, 2]: \begin{cases} \|u_h - u\|_{L^p(\Omega)} \lesssim \|u_h - u_h^*\|_{J,p} + h^{s+1} |u|_{W^{s+1,p}(\Omega)}, \\ \|\mathbf{q}_h - \mathbf{q}\|_{L^p(\Omega)} + \|[u_h - u]\|_{L^p(\Gamma^o, \eta h_e^{1-p})} \lesssim \|u_h - u_h^*\|_{J,p} + h^s |u|_{W^{s+1,p}(\Omega)}, \\ \|\sigma_h - \sigma\|_{L^p(\Omega)} \lesssim \|\mathbf{q}_h - \mathbf{q}\|_{L^p(\Omega)}^{p-1}, \\ \|u_h - u_h^*\|_{J,p} \lesssim C_{gd,f,g_N,n}^{2-p} (h^{s(p-1)} |u|_{W^{s+1,p}(\Omega)}^{p-1} + h^r |\sigma|_{W^{r,p}(\Omega)}). \end{cases}$$

$$\text{For } p \in [2, +\infty): \begin{cases} \|u_h - u\|_{L^p(\Omega)} \lesssim \|u_h - u_h^*\|_{J,p} + h^{s+1} |u|_{W^{s+1,p}(\Omega)}, \\ \|\mathbf{q}_h - \mathbf{q}\|_{L^p(\Omega)} + \|[u_h - u]\|_{L^p(\Gamma^o, \eta h_e^{1-p})} \lesssim \|u_h - u_h^*\|_{J,p} + h^s |u|_{W^{s+1,p}(\Omega)}, \\ \|\sigma_h - \sigma\|_{L^p(\Omega)} \lesssim C_{gd,f,g_N,n}^{p-2} \|\mathbf{q}_h - \mathbf{q}\|_{L^p(\Omega)}, \\ \|u_h - u_h^*\|_{J,p} \lesssim h^{\frac{s}{p-1}} C_{gd,f,g_N,n}^{p-1} |u|_{W^{s+1,p}(\Omega)}^{\frac{1}{p-1}} + h^{\frac{r}{p-1}} |\sigma|_{W^{r,p}(\Omega)}^{\frac{1}{p-1}} + h^s |u|_{W^{s+1,p}(\Omega)}. \end{cases}$$

Here, the hidden constant $C > 0$ is independent of h . $C_{gd,f,g_N,n}$ is defined to be

$$C_{gd,f,g_N,n} := \|g_D\|_{W^{1,p}(\Gamma^D)} + \|f\|_{L^p(\Omega)} + \|\mathbf{g}_N \cdot \mathbf{n}\|_{L^p(\Gamma^N)}.$$

Numerical examples

Domain: $\Omega = \{(x, y) \in [-1, 1]^2 : x - y \leq 1\}$. Let $r(x, y) = \sqrt{x^2 + y^2}$. Take the exact solution [Barrett and Liu 1993]; [Cockburn and Shen 2016] as

$$u(x, y) = \frac{p-1}{(\sigma+2)^{\frac{1}{p-1}}} \frac{1-r(x, y)^{\frac{\sigma+p}{p-1}}}{\sigma+p}.$$

We consider two groups of parameters: $(\sigma, p) = (0, 1.5)$ and $(\sigma, p) = (7, 4)$.

Case 1: $(\sigma, p) = (0, 1.5)$

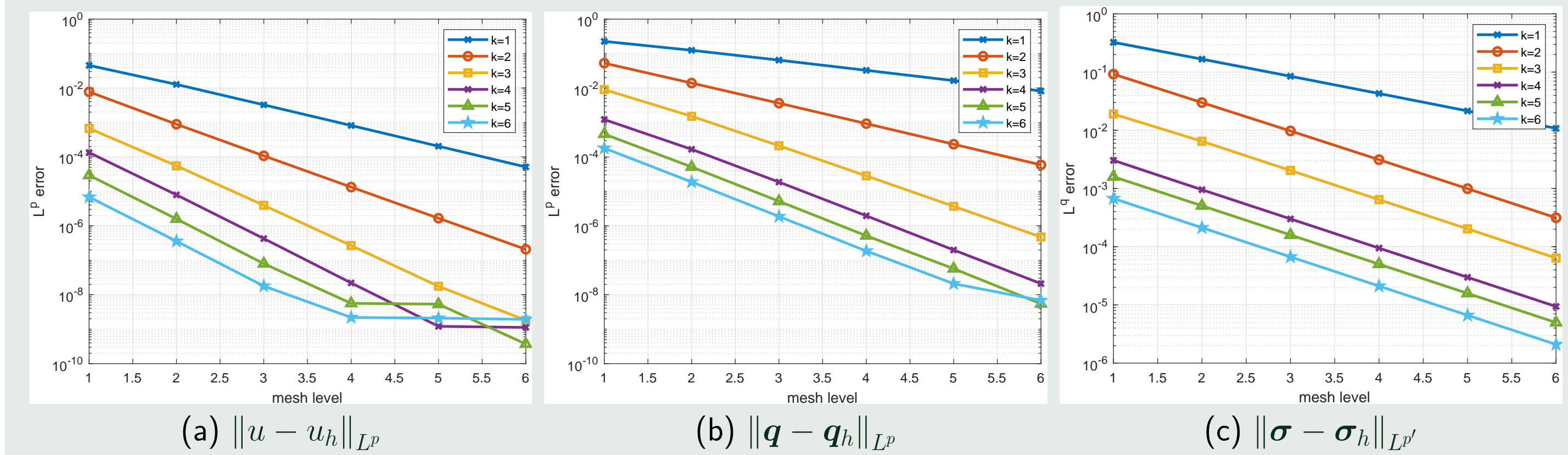


Figure 1. Error convergence history. Parameters: $\sigma = 7, p = 4$.

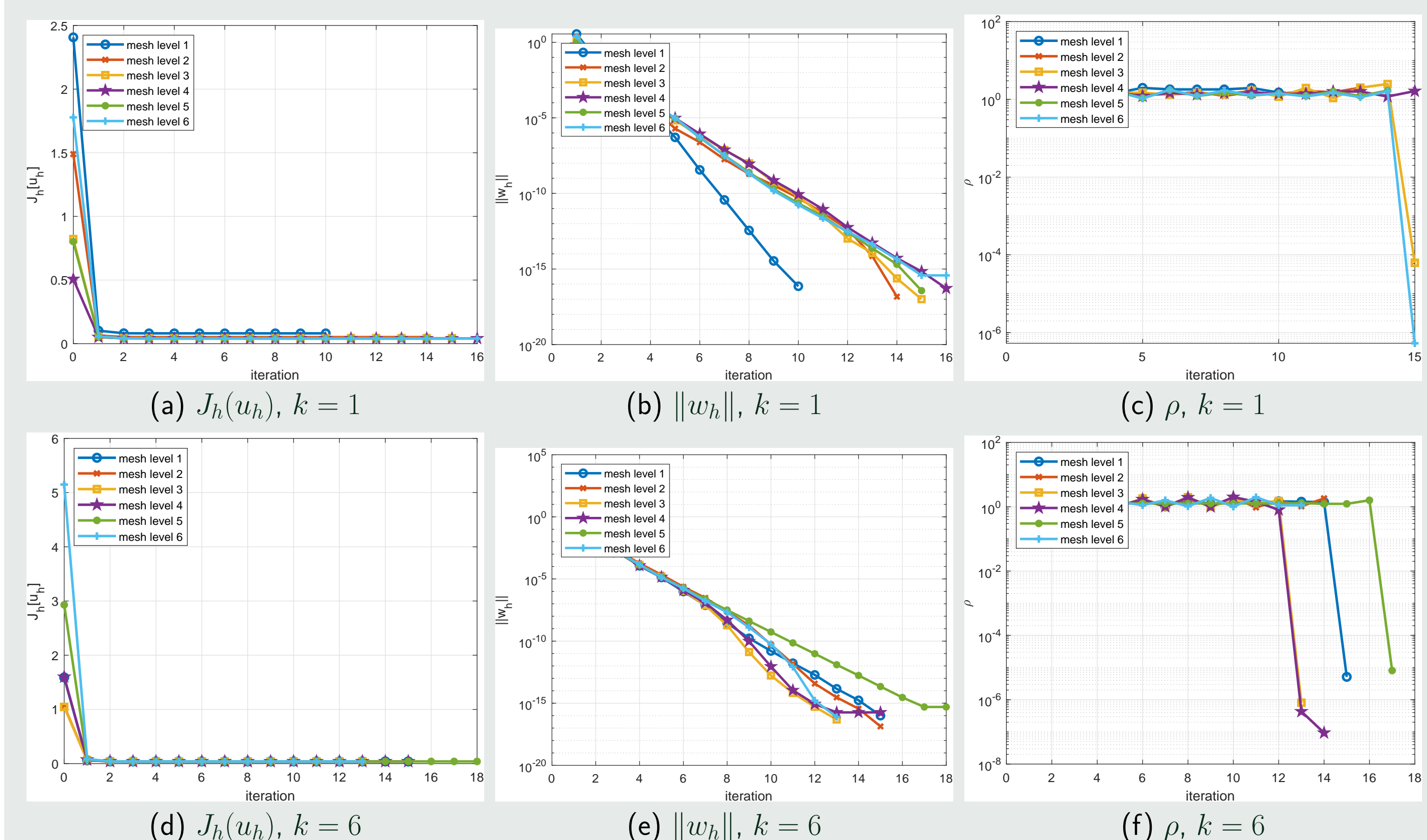


Figure 2. Gradient descent convergence history. Parameters: $\sigma = 0, p = 1.5$.

Case 2: $(\sigma, p) = (7, 4)$

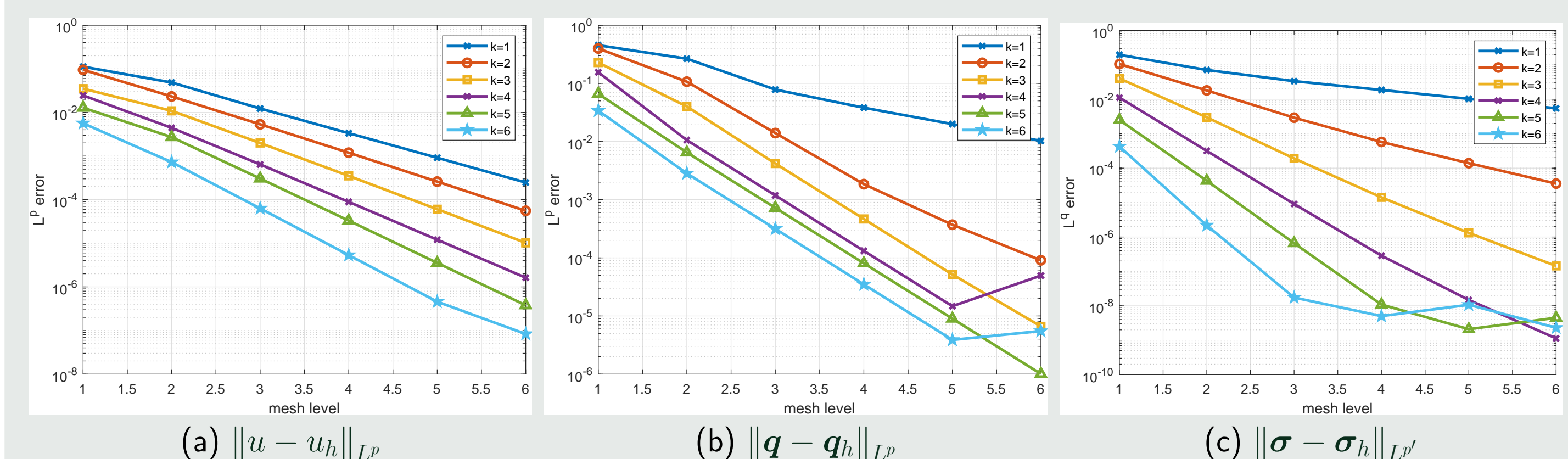


Figure 3. Error convergence history. Parameters: $\sigma = 7, p = 4$.

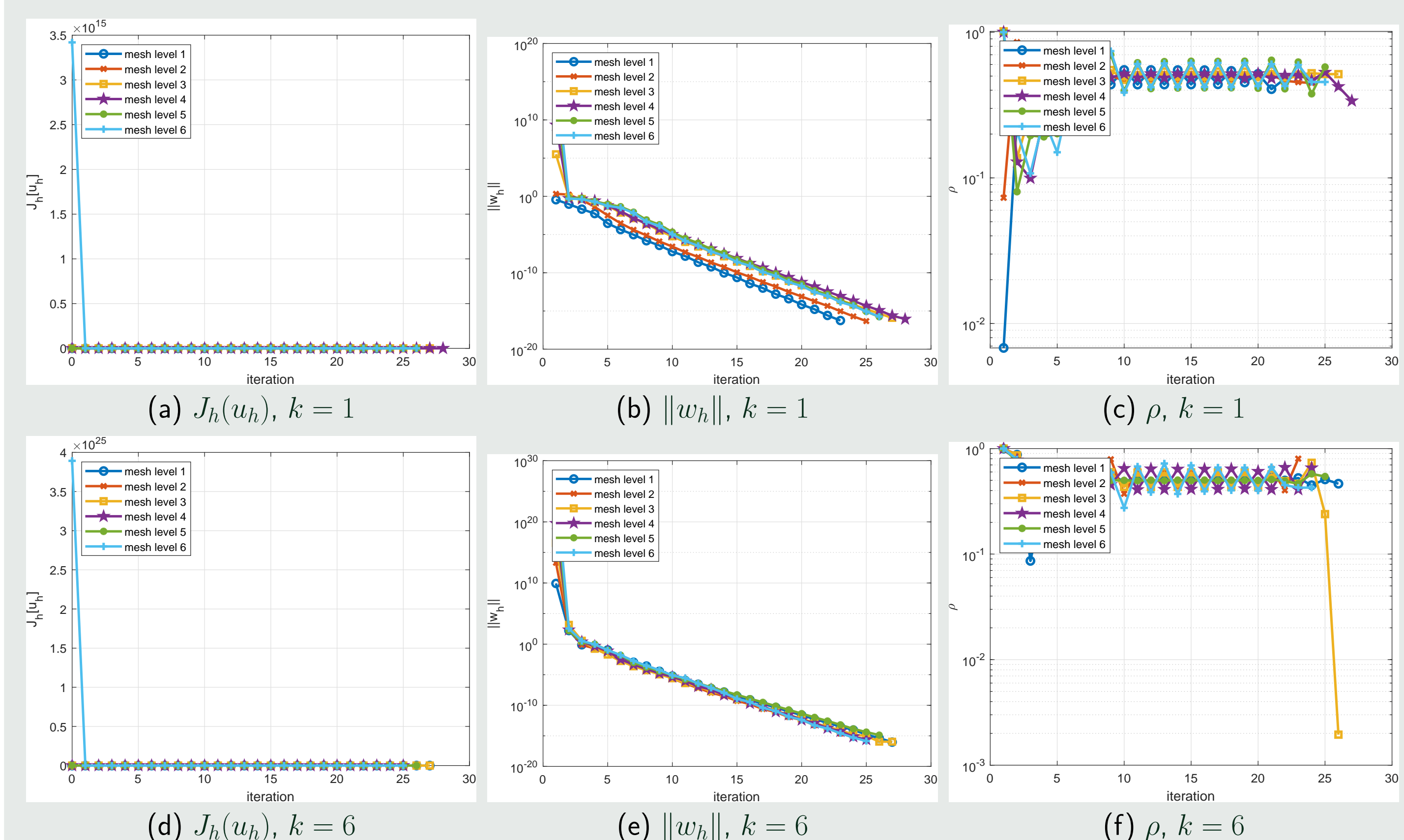


Figure 4. Gradient descent convergence history. Parameters: $\sigma = 7, p = 4$.

References

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